

## Blgebra

$$\sin n\pi = 0$$

$$1 - \cos n\pi = 2 \text{ for odd } n$$

$$\arctan\left(\frac{1}{\sqrt{3}}\right) = \frac{\pi}{6}, \arctan(\sqrt{3}) = \frac{\pi}{3}$$

$$\sin(x \pm y) = \sin x \cos y \pm \cos x \sin y$$

$$\cos(x \pm y) = \cos x \cos y \mp \sin x \sin y$$

$$\sin x \sin y = \frac{1}{2}[\cos(x-y) - \cos(x+y)]$$

$$\cos x \cos y = \frac{1}{2}[\cos(x-y) + \cos(x+y)]$$

$$\sin x \cos y = \frac{1}{2}[\sin(x-y) + \sin(x+y)]$$

$$\sin a \pm \sin b = 2 \sin \frac{a+b}{2} \cos \frac{a \mp b}{2}$$

$$\cos a + \cos b = 2 \cos \frac{a+b}{2} \cos \frac{a-b}{2}$$

$$\cos a - \cos b = -2 \sin \frac{a+b}{2} \sin \frac{a-b}{2}$$

$$C \cos(\omega_0 t + \theta) = C \cos(\theta) \cos(\omega_0 t) - C \sin(\theta) \sin(\omega_0 t)$$

$$C \sin(\omega_0 t + \theta) = C \sin(\theta) \cos(\omega_0 t) + C \cos(\theta) \sin(\omega_0 t)$$

$$\theta = \tan^{-1}(-\frac{b}{a}), \pm\pi \text{ when } a < 0$$

$$\sin t = \cos(t - \frac{\pi}{2})$$

$$-\cos t = \sin(t - \frac{\pi}{2})$$

$$\cos x = \frac{1}{2}[e^{jx} + e^{-jx}]$$

$$\sin x = \frac{1}{2j}[e^{jx} - e^{-jx}]$$

$$e^{j\omega t} = \cos(\omega t) + j \sin(\omega t)$$

$$z^* = a - jb = re^{-j\theta}$$

$$u^*v^* = (uv)^*$$

$$\angle z = \tan^{-1}(\frac{b}{a}), \pm\pi \text{ in Q2 and Q3}$$

$$z^{\frac{1}{n}} = r^{\frac{1}{n}} e^{j\frac{\theta+2\pi m}{n}}$$

$$(s+a)(s+b)(s+c) = s^3 + (a+b+c)s^2 + (ab+bc+ca)s + abc$$

## Integrals

$$\int \cos^2 at dt = \frac{t}{2} + \frac{\sin 2at}{4a}$$

$$\int t \cos at dt = \frac{1}{a^2}(\cos at + at \sin at)$$

$$\int t \sin at dt = \frac{1}{a^2}(\sin at - at \cos at)$$

$$\int t^2 \cos at dt = \frac{1}{a^3}(2at \cos at - 2 \sin at + a^2 t^2 \sin at)$$

$$\int t^2 \sin at dt = \frac{1}{a^3}(2at \sin at + 2 \cos at - a^2 t^2 \cos at)$$

$$\int te^{at} dt = \frac{1}{a^2}e^{at}(at - 1)$$

$$\int t^2 e^{at} dt = \frac{1}{a^3}e^{at}(a^2 t^2 - 2at + 2)$$

$$\int e^{at} \cos bt dt = \frac{1}{a^2+b^2}e^{at}(a \cos bt + b \sin bt)$$

$$\int e^{at} \sin bt dt = \frac{1}{a^2+b^2}e^{at}(a \sin bt - b \cos bt)$$

$$\int \frac{1}{x^2+a^2} dx = \frac{1}{a} \tan^{-1} \frac{x}{a}$$

## Signals

$$\mathcal{E}_f = \int_{-\infty}^{\infty} |f(t)|^2 dt \text{ (complex);}$$

$$P_f = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |f(t)|^2 dt;$$

rms power =  $\sqrt{P_f}$

Cont; analog; periodic (extension); (non/anti)causal; energy/power (both); deterministic/stochastic (info)

$$\int f(t) \cdot \delta(t-t_0) dt = f(t_0) \text{ (f continuous at } t_0)$$

$f(2x-6)$ : shift by 6, scale by 2;

$f(2(x-6))$ : scale by 2, shift by 6

$$f_e(t) = \frac{1}{2}[f(t) + f(-t)]$$

$$f_o(t) = \frac{1}{2}[f(t) - f(-t)]$$

## Systems

$$\mathcal{T}: \sum_{k=0} a_k D^k y(t) = \sum_{l=0} b_l D^l f(t)$$

$$\text{Linear } \mathcal{T}[kf_1(t) + f_2(t)] = ky_1(t) + y_2(t).$$

Lin if  $a_k, b_l$  are not functions of  $y(t), f(t)$

$$\text{E. } \sin \dot{y}(t) + t^2 y(t) = (t+3)f(t)$$

$$\text{Time-inv } \mathcal{T}[f(t-\tau)] = y(t-\tau).$$

$a_k, b_l$  indep of  $t$  (const coeff)

Let  $g(t) \equiv f(t-\tau)$ , find  $z(t) = \mathcal{T}[g(t)]$ , cmp  $y(t-\tau)$

**Causal**  $y(t)$  dep only on  $f(\tau)$ ,  $\tau \leq t$ . Compare  $t$  and  $\tau$ .

**Instantaneous**  $y$  only dep  $f$  at present (no  $\int$ , no memory)

**Invertible** given  $y(t)$ , we can know  $f(t)$  (ideal diff is not)

## Conv prop

$$c(t) \equiv \int_{-\infty}^{\infty} f(\tau) g(t-\tau) d\tau$$

$$c[n] \equiv \sum_{m=-\infty}^{\infty} f[m] g[n-m]$$

$$f * g = g * f$$

$$f * (g+h) = f * h + g * h$$

$$f * (g * h) = (f * g) * h$$

pf:  $f * (g * h) = f * (h * g)$

$$= \int f(\tau_1) \int h(\tau_2) g(t - \tau_2 - \tau_1) d\tau_2 d\tau_1 \\ = \int h(\tau_2) \int f(\tau_1) g(t - \tau_1 - \tau_2) d\tau_1 d\tau_2$$

$$f(t-T_1) * g(t-T_2) = c(t-T_1-T_2)$$

$$f(at) * g(at) = |\frac{1}{a}| c(at) \text{ (even/odd)}$$

$$f^{(m)}(t) * g^{(n)}(t) = c^{(m+n)}(t)$$

pf:  $\dot{f}(\tau) = \lim_{T \rightarrow 0} f(\tau) - f(\tau - T)$

Graph: shift **left** by **+t**, and reflect;

Every  $\tau$  replaced by **t - τ**; Reverted

## Conv table

$$f(t) * \delta(t-T) = f(t-T)$$

$$u(t) * u(t) = t u(t)$$

$$e^{at} u(t) * u(t) = \frac{1-e^{at}}{-a} u(t)$$

$$e^{at} u(t) * e^{bt} u(t) = \frac{e^{at}-e^{bt}}{a-b} u(t)$$

$a = b, te^{at} u(t)$

$$e^{at} u(t) * e^{bt} u(-t) = \frac{e^{at} u(t) + e^{bt} u(-t)}{b-a}$$

$\Re(b) > \Re(a)$

$$te^{at} u(t) * e^{at} u(t) = \frac{1}{2} t^2 e^{at} u(t)$$

$$t^m u(t) * t^n u(t) = \frac{m! n!}{(m+n+1)!} t^{m+n+1} u(t)$$

Don't forget  $[u(t+T_1) - u(t-T_2)]$  term

## LTI response

$$Q(D)y(t) = P(D)f(t), \text{ typically integrating } f$$

Assume causal input  $f(t)u(t)$

$y_{zs}(t) = f(t) * h(t)$  from input

$$y_{zs}(0^-) = 0, y_{zs}(0^+) \neq 0$$

Let  $h(t) = \mathcal{T}[\delta(t)]$  (impulse response)

$$y_{zs}(t) = \mathcal{T}[f(t)] = \mathcal{T}[f(t) * \delta(t)]$$

$$= \mathcal{T}[\lim \sum f(n\Delta\tau) \delta(t-n\Delta\tau) \Delta\tau]$$

$$= \lim \sum f(n\Delta\tau) h(t-n\Delta\tau) \Delta\tau = f * h$$

$y_{zi}(t)$  from ini,  $f(t) = 0, Qy_{zi}(t) = 0$

$$y_{zi}(0^-) = y_{zi}(0^+), y_{zi}'(0^-) = y_{zi}'(0^+)$$

## Ortho set

$$\mathcal{E}_e = \int_{t_1}^{t_2} [e(t)]^2 dt$$

$$= \int_{t_1}^{t_2} f^2(t) dt - 2 \sum c_i \int_{t_1}^{t_2} f(t) x_i(t) dt + \int_{t_1}^{t_2} (\sum c_i x_i(t))^2 dt$$

$$= \mathcal{E}_f - 2 \sum c_i \langle f, x_i \rangle$$

$$+ (\sum c_i^2 \int_{t_1}^{t_2} x_i(t)^2 dt + \sum_{i \neq j} c_i c_j \int_{t_1}^{t_2} x_i(t) x_j(t) dt)$$

$$\frac{\partial \mathcal{E}_e}{\partial c_i} = 0 = -2 \langle f(t), x_i(t) \rangle + 2 \mathcal{E}_i c_i$$

$$\mathcal{E}_e^{\min} = \mathcal{E}_f - \sum_{i=1}^N c_i^2 \mathcal{E}_i$$

$$c_i = \frac{1}{\mathcal{E}_i} \langle f, x_i \rangle = \frac{\int f(t) x_i(t) dt}{\int x_i^2(t) dt}$$

For ortho,  $E_z = E_x + E_y$

$$|u+v|^2 = |u|^2 + |v|^2 + u^*v + v^*u$$

$$\langle x(t), y(t) \rangle = \int_{t_1}^{t_2} x(t) y(t)^* dt = \int_{t_1}^{t_2} x(t) y(t) dt \text{ if real}$$

Use prod → sum identities

## FS

$$a_0 = \frac{1}{T_0} \int_{T_0} f(t) dt$$

$$a_n = \frac{2}{T_0} \int_{T_0} f(t) \cos(n\omega_0 t) dt$$

$$b_n = \frac{2}{T_0} \int_{T_0} f(t) \sin(n\omega_0 t) dt$$

Energy:  $T_0$  for  $n = 0$ ;  $T_0/2$  else

$$\text{Half wave sym } f(t - \frac{T_0}{2}) = -f(t)$$

$$a_{n_{\text{odd}}} = \frac{4}{T_0} \int_0^{T_0/2} f(t) \cos(n\omega_0 t) dt$$

$$f(t) = \sum_{n=-\infty}^{\infty} F_n e^{jn\omega_0 t}$$

$$F_n = \frac{1}{T_0} \int_{T_0} f(t) e^{-jn\omega_0 t} dt$$

$$C_n \cos(n\omega_0 t + \theta_n) = \frac{C_n}{2} (e^{j(n\omega_0 t + \theta_n)} + e^{-j(n\omega_0 t + \theta_n)}) \\ = (\frac{C_n}{2} e^{j\theta_n}) e^{jn\omega_0 t} + (\frac{C_n}{2} e^{-j\theta_n}) e^{-jn\omega_0 t}$$

$$F_n = \frac{C_n}{2} e^{j\theta_n} = \frac{1}{2}(a_n - jb_n) = |F_n| e^{j\angle F_n}$$

$$F_{-n} = \frac{C_n}{2} e^{-j\theta_n} = \frac{1}{2}(a_n + jb_n)$$

## Existence

Weak: finite  $\int$ , fin bounds  $a, b$ , fin power

Strong: fin min/max/discont over  $T_0$ ,  $\rightarrow \frac{f(t_0^+) + f(t_0^-)}{2}$

## FS prop

$$\text{Time shift } f(t - t_0) \rightarrow F_n e^{-jn(\omega_0 t_0)}$$

$|F_n|$  same;  $\angle F_n$  shifted by  $-(\omega_0 t_0)n$

$$\text{Reversal } f(-t) \rightarrow F_{-n}$$

$$\text{Scaling } T = \frac{T_0}{a}, \omega = a\omega_0$$

$$\text{Multiplication (same } T_0\text{): } f(t)g(t) \rightarrow F_n * G_n$$

$$\begin{aligned} & \frac{1}{T_0} \int_{T_0} f(t)g(t) e^{jn\omega_0 t} dt \\ &= \frac{1}{T_0} \int (\sum F_m e^{jm\omega_0 t})(\sum G_k e^{jk\omega_0 t}) e^{-jn\omega_0 t} dt \\ &= \sum_m \sum_k F_m G_k \frac{1}{T_0} \int_{T_0} e^{j(m+k-n)\omega_0 t} dt \\ &= \sum_m \sum_k F_m G_k \langle e^{j(m+k)\omega_0 t}, e^{jn\omega_0 t} \rangle \\ &= \sum_{k=-\infty}^{\infty} G_k F_{n-k} \end{aligned}$$

$$\text{Conjugation } f(t)^* = F_{-n}^*$$

$$\text{Parseval (power sig): } P_f = \frac{1}{T_0} \int_{T_0} f(t) f(t)^* dt$$

$$= \frac{1}{T_0} \int_{T_0} (\sum_n F_n e^{jn\omega_0 t})(\sum_m F_m e^{jm\omega_0 t})^* dt$$

$$= \sum_n \sum_m F_n F_m^* \frac{1}{T_0} \int_{T_0} e^{j(n-m)\omega_0 t} dt$$

$$= \sum_n |F_n|^2 \cdot 1$$

$f$  real  $\rightarrow |F|$  even,  $\angle F$  odd

$f$  real, even  $\rightarrow F$  real, even;  $F_{-n} = F_n = F_n^*$

$f$  real, odd  $\rightarrow F$  imaginary, odd;  $-F_{-n} = F_n = -F_n^*$

$$f_e(t) \rightarrow \Re\{F_n\}$$

$$f_o(t) \rightarrow j \Im\{F_n\}$$

## Common FS

$$(A = 1, T = 2\pi, \omega = 1)$$

$$\text{Square } \frac{4}{\pi} (\cos t - \frac{1}{3} \cos 3t + \frac{1}{5} \cos 5t - \dots) \\ \frac{4}{\pi} (\sin t + \frac{1}{3} \sin 3t + \frac{1}{5} \sin 5t + \dots)$$

$$\text{Triangle } \frac{8}{\pi^2} (\sin t - \frac{1}{9} \sin 3t + \frac{1}{25} \sin 5t - \dots) \\ \frac{8}{\pi^2} (\cos t + \frac{1}{9} \cos 3t + \frac{1}{25} \cos 5t + \dots)$$

$$\text{Sawtooth } \frac{2}{\pi} (\sin t - \frac{1}{2} \sin 2t + \frac{1}{3} \sin 3t - \dots) \\ \frac{2}{\pi} (-\sin t - \frac{1}{2} \sin 2t - \frac{1}{3} \sin 3t - \dots)$$

$$\delta \text{ train } \delta_{T_0}(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_0) \\ \frac{1}{T_0} \sum_{n=-\infty}^{\infty} e^{jn\omega_0 t}$$

## FT

$$\text{Let } F(\omega) \equiv \int f(t) e^{-j\omega t} dt$$

$$F_n = \frac{1}{T_0} \int_{T_0} f(t) e^{-jn\omega_0 t} dt$$

Limit as  $\omega_0 = \Delta\omega \rightarrow 0$ ,

$$F_n = \frac{\Delta\omega}{2\pi} \int_{-\infty}^{\infty} f(t) e^{-jn\Delta\omega t} dt \equiv \frac{\Delta\omega}{2\pi} F(n\Delta\omega)$$

$$f_{T_0}(t) = \sum F_n e^{jn\omega_0 t} = \sum \frac{\Delta\omega}{2\pi} F(n\Delta\omega) e^{jn\Delta\omega t}$$

$$f(t) = \lim_{T_0 \rightarrow \infty} f_{T_0}(t) = \frac{1}{2\pi} \int F(\omega) e^{j\omega t} d\omega$$

$$F(\omega) = |F(\omega)| e^{j\angle F(\omega)}$$

Real signals: amp and phase symmetry

Existence: weak: energy signal ( $|e^{-j\omega t}| = 1$ )

Strong: fin num max/min/discont

## FT Table

$$\delta(t) \rightarrow 1$$

$$1 \rightarrow 2\pi\delta(\omega)$$

$$e^{j\omega_0 t} \rightarrow 2\pi\delta(\omega - \omega_0)$$

$$\cos\omega_0 t \rightarrow \pi[\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]$$

$$\sin\omega_0 t \rightarrow j\pi[\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$$

$$\sum \delta(t - nT_0) \rightarrow \omega_0 \sum \delta(\omega - n\omega_0)$$

$$e^{-at} u(t) \rightarrow \frac{1}{a+j\omega}$$

$$e^{-a|t|} \rightarrow \frac{2a}{a^2 + \omega^2}$$

$$u(t) = \lim_{a \rightarrow 0} e^{-at} u(t) \rightarrow \lim \frac{1}{a+j\omega}$$

$$= \lim(\frac{a}{a^2 + \omega^2} - j\frac{\omega}{a^2 + \omega^2}) = \pi\delta(\omega) + \frac{1}{j\omega}$$

$$\text{sgn}(t) \rightarrow \frac{2}{j\omega}$$

$$t^n e^{-at} u(t) \rightarrow \frac{n!}{(a+j\omega)^{n+1}}$$

$$\cos\omega_0 t u(t) \rightarrow \frac{\pi}{2}(\delta(\omega - \omega_0) + \delta(\omega + \omega_0)) + \frac{j\omega}{\omega_0^2 - \omega^2}$$

$$\sin\omega_0 t u(t) \rightarrow \frac{\pi}{2}j(\delta(\omega - \omega_0) - \delta(\omega + \omega_0)) + \frac{\omega_0}{\omega_0^2 - \omega^2}$$

$$e^{-at} \cos\omega_0 t u(t) \rightarrow \frac{a+j\omega}{(a+j\omega)^2 + \omega_0^2}$$

$$e^{-at} \sin\omega_0 t u(t) \rightarrow \frac{\omega_0}{(a+j\omega)^2 + \omega_0^2}$$

$$\text{rect}(\frac{t}{\tau}) \rightarrow \tau \text{sinc}(\frac{\pi}{2}\omega)$$

$$\frac{W}{\pi} \text{sinc}(Wt) \rightarrow \text{rect}(\frac{\omega}{2W})$$

$$\triangle(\frac{t}{\tau}) \rightarrow \frac{\tau}{2} \text{sinc}^2(\frac{\pi}{4}\omega)$$

$$\frac{W}{2\pi} \text{sinc}^2(\frac{W}{2}t) \rightarrow \triangle(\frac{\omega}{2W})$$

$$[\omega^2 r(\frac{\omega}{2\omega_0})] \leftarrow \frac{1}{2\pi} \frac{e^{j\omega t}}{(jt)^3} (-\omega^2 t^2 - 2j\omega t + 2)_{-\omega_0}^{\omega_0} \\ = \frac{(\omega_0^2 t^2 - 2) \sin\omega_0 t + 2\omega_0 t \cos\omega_0 t}{\pi t^3}$$

$$[\frac{|\omega|}{\omega_0} \text{rect}(\frac{\omega}{2\omega_0})] \leftarrow \frac{\cos\omega_0 t + \omega_0 t \sin\omega_0 t - 1}{\omega_0 \pi t^2}$$

## Frequency domain prop

Linearity

$$\text{Time shift } f(t - t_0) \rightarrow F(\omega) e^{-jt_0\omega}$$

$|F|$  unchanged;  $\angle F = -t_0\omega$ , lin shift

$$\text{Freq shift } f(t) e^{j\omega_0 t} \rightarrow F(\omega - \omega_0)$$

$$\text{Duality } f(t) \rightarrow F(\omega), F(t) \rightarrow 2\pi f(-\omega)$$

$$\text{pf. } f(t) = \frac{1}{2\pi} \int F(\lambda) e^{jt\lambda} d\lambda \\ 2\pi f(-t) = \int F(\lambda) e^{-tj\lambda} d\lambda = \mathcal{F}[F(\lambda)]$$

$$\text{Reversal } f(-t) \rightarrow F(-\omega)$$

$$\text{Scaling } f(at) \rightarrow \frac{1}{|a|} F(\frac{\omega}{a})$$

$$\text{Convolution } f * g \rightarrow FG, fg \rightarrow \frac{1}{2\pi} F * G$$

$$\mathcal{F}[f * g] = \int e^{-j\omega t} \int f(\tau) g(t - \tau) d\tau dt \\ = \int f(\tau) \mathcal{F}[g(t - \tau)] d\tau$$

$$= \int f(\tau) G(\omega) e^{-j\omega\tau} d\tau$$

$$\frac{1}{2\pi} \mathcal{F}^{-1}[F * G] = (\frac{1}{2\pi})^2 \int e^{j\omega t} \int F(\lambda) G(\omega - \lambda) d\lambda d\omega$$

$$\text{Diff } f^{(n)}(t) \rightarrow (j\omega)^n F(\omega) \text{ (diff } e^{j\omega t})$$

$$\text{Int } \int_{-\infty}^t f(\tau) d\tau \rightarrow \frac{1}{j\omega} F(\omega) + \pi F(0) \delta(\omega)$$

$$f = f(t) * u(t) \rightarrow F(\omega) U(\omega)$$

$$U(\omega) = \lim \frac{1}{a+j\omega} = \lim(\frac{a}{a^2 + \omega^2} - j\frac{\omega}{a^2 + \omega^2}) \\ = \pi\delta(\omega) + \frac{1}{j\omega} (\int \frac{a}{\omega^2 + a^2} d\omega = \tan^{-1} = \pi)$$

$$\text{Conjugation } f(t)^* \rightarrow F(-\omega)^*$$

$$\text{Symmetry Re} \rightarrow \text{mag even, phase odd } (F(-\omega) = F(\omega)^*) \\ \text{real, even} \rightarrow \text{real, even}; \text{real, odd} \rightarrow \text{imaginary, odd}$$

$$f \text{ even: } F(\omega) = 2 \int_0^\infty f(t) \cos(\omega t) dt$$

$$f \text{ odd: } F(\omega) = -2j \int_0^\infty f(t) \sin(\omega t) dt$$

$$a > 0$$

$$a > 0$$

$$a > 0$$

$$a > 0$$

## Parseval

$$\begin{aligned} E_f &= \int |f(t)|^2 dt = \frac{1}{2\pi} \int |F(\omega)|^2 d\omega \text{ for energy sig} \\ &= \int f f^* dt = \int f(t) \mathcal{F}^{-1}[F(-\omega)^*] dt \\ &= \int f(t) \frac{1}{2\pi} \int F(-\omega)^* e^{j\omega t} d\omega dt \\ &= \frac{1}{2\pi} \int f(t) \int F(\lambda)^* e^{-jt\lambda} d\lambda dt \\ &= \frac{1}{2\pi} \int F(\lambda)^* \int f(t) e^{-jt\lambda} dt d\lambda \end{aligned}$$

$$\Delta E_f = \frac{2}{2\pi} \int_{\omega_1}^{\omega_2} |F(\omega)|^2 d\omega$$

$$\text{Autocorrelation } \psi_f(t) \equiv \int f(\tau) f(\tau - t) d\tau \rightarrow |F(\omega)|^2$$

## Modulation

$$m(t) \cos(\omega_c t) \rightarrow \frac{1}{2} [M(\omega + \omega_c) + M(\omega - \omega_c)]$$

$$e(t) = m(t) \cos^2 \omega_c t$$

$$E(\omega) = \frac{1}{2} M + \frac{1}{4} [M(\omega + 2\omega_c) + M(\omega - 2\omega_c)] \rightarrow \text{LPF}$$

SSB 1/4 gain

$$\begin{aligned} \phi_{\text{AM}}(t) &= [A + f(t)] \cos(\omega_0 t) \\ A &\geq f(t) \text{ for all } t \end{aligned}$$

$$\text{modulation index } \mu \equiv f_{\max}/A$$

$\mu = \infty$ , suppressed carrier;  $\mu = 1$ , marginal

## LTIC sys trans, (marginally) stable

$$\text{Let } e^{j\omega t} \Rightarrow H(\omega) e^{j\omega t}$$

$$\lim \sum \frac{F(n\Delta\omega)\Delta\omega}{2\pi} e^{jn\Delta\omega t} \Rightarrow \lim \sum \frac{F(n\Delta\omega)H(n\Delta\omega)\Delta\omega}{2\pi} e^{jn\Delta\omega t}$$

$$y(t) = \frac{1}{2\pi} \int F(\omega) H(\omega) e^{j\omega t} d\omega$$

$$Y(\omega) = F(\omega) H(\omega)$$

$$\text{Distortionless } y(t) = kf(t - t_d), \text{ so } H(\omega) = ke^{-j\omega t_d}$$

Payley-Wiener  $H$  realizable,  $h$  causal iff

$$\int \frac{|\ln|H(\omega)||}{1+\omega^2} d\omega < \infty \text{ (consecutive 0s)}$$

$$\text{Truncate } \hat{h}(t) = h(t)u(t)$$

## Periodic FT

$$f(t) = \sum_n F_n e^{jn\omega_0 t}$$

$$\mathcal{F}[f(t)] = 2\pi \sum_n F_n \delta(\omega - n\omega_0)$$

$$Y = F(\omega) H(\omega) = 2\pi \sum F_n H(n\omega_0) \delta(\omega - n\omega_0)$$

$$Y_n \equiv F_n H(n\omega_0). \text{ Periodic with same } \omega_0$$

$$\text{Eigen: } f(t) = e^{j\omega_0 t}, Y_1 = H(1\omega_0), y(t) = H(1\omega_0) e^{j\omega_0 t}$$

$$f(t) = \cos(\omega_0 t + \theta), \text{ assume } h(t) \text{ real}$$

$$\begin{aligned} y &= \frac{1}{2} (e^{j(\theta+\omega_0 t)} H(\omega_0) + e^{-j(\theta+\omega_0 t)} H(-\omega_0)) \\ &= [H(\omega_0)] \cos(\omega_0 t + \theta + \angle H(\omega_0)) \end{aligned}$$

$$\begin{aligned} \cos 2t * e^{-3t} u(t) &\equiv f * h \\ &= |H(2)| \cos(2t + \angle H(2)) \end{aligned}$$

## Sampling

$$\begin{aligned} \bar{f}(t) &\equiv f(t) \delta_{T_s}(t) = \sum f(nT_s) \delta(t - nT_s) \\ F(\omega) &= \frac{1}{2\pi} F(\omega) * [\frac{2\pi}{T_s} \sum \delta(\omega - n\omega_s)] = \frac{1}{T_s} \sum F(\omega - n\omega_s) \end{aligned}$$

$$\omega_s \geq 4\pi B, F_s \geq F_N \equiv 2B$$

Intrapolation when  $F_s = 2B$

$$F(\omega) = \bar{F}(\omega) T_s \text{ rect}\left(\frac{\omega}{4\pi B}\right)$$

$$\begin{aligned} \text{If } F_s = 2B, f(t) &= \bar{f}(t) * \frac{2B}{F_s} \text{ sinc}(2\pi B t) \\ &= \sum_n f(nT_s) \delta(t - nT_s) * \text{sinc}(2\pi B t) \\ &= \sum_n f(nT_s) \text{sinc}(2\pi B t - n\pi) \end{aligned}$$

ana FS, with basis sinc, weighted sample sum

$$\text{If } F_s > 2B, f(t) = \sum f(nT_s) w(t - nT_s) \quad \text{not sinc weight for some relaxed LP filter } w(t)$$

Anti-alias before sampling: LPF of  $F_s/2$

## Practical sampling

$$p_T(t) = \frac{\tau}{T_s} + \sum \left( \frac{2}{\pi n} \sin(n\pi \frac{\tau}{T_s}) \right) \cos(n\omega_s t)$$

$$P_T(\omega) = 2\pi \frac{\tau}{T_s} \delta(\omega) + \sum \frac{\pi^2 \sin(\dots)}{\pi n} [\delta(\omega + n\omega_s) + \delta(\omega - n\omega_s)]$$

## LT

$$\mathcal{L}[-e^{-at} u(-t)] = \mathcal{L}[e^{-at} u(t)], \text{ except ROC}$$

If sig are causal,  $\mathcal{L}$  is 1-to-1

$$\begin{aligned} \text{Unilateral: } \mathcal{L}[f] &= \int_0^\infty f(t) e^{-st} dt \\ &= \int [f(t) e^{-\sigma t}] e^{-j\omega t} dt \end{aligned}$$

$\sigma_0$ : smallest  $\sigma$  to make integral converge

## Uni LT Table

Watch ROC!!

$$\delta(t) \rightarrow 1$$

$$u(t) \rightarrow \frac{1}{s}$$

$$t^n u(t) \rightarrow \frac{n!}{s^{n+1}}$$

$$e^{\lambda t} u(t) \rightarrow \frac{1}{s-\lambda}$$

$$t^n e^{\lambda t} u(t) \rightarrow \frac{n!}{(s-\lambda)^{n+1}}$$

$$\frac{1}{(n-1)!} t^{n-1} e^{\lambda t} u(t) \rightarrow \frac{1}{(s-\lambda)^n}$$

$$e^{-at} \cos(bt) u(t) \rightarrow \frac{s+a}{(s+a)^2 + b^2}$$

$$e^{-at} \sin(bt) u(t) \rightarrow \frac{b}{(s+a)^2 + b^2}$$

$$re^{-at} \cos(bt + \theta) u(t) \rightarrow \frac{(r \cos \theta)s + (ar \cos \theta - br \sin \theta)}{s^2 + 2as + (a^2 + b^2)}$$

$$2re^{-at} \cos(bt + \theta) u(t) \rightarrow \frac{re^{j\theta}}{s - (-a + jb)} + \frac{re^{-j\theta}}{s - (-a - jb)}$$

$$\begin{aligned} e^{-at} [A \cos(bt) + \frac{B-Aa}{b} \sin(bt)] u(t) &= \frac{\sqrt{A^2 + B^2 - 2ABa}}{b} e^{-at} \cos\left(bt + \tan^{-1} \frac{Aa-B}{Ab}\right) u(t) \\ &\rightarrow \frac{As+B}{s^2 + 2as + c} \quad b \equiv \sqrt{c - a^2} \end{aligned}$$

## LT Prop

Linearity

$$\text{Time delay } f(t-t_0) u(t-t_0) \rightarrow F(s) e^{-st_0} \quad \text{ROC same}$$

ROC  $\cap$

$$t_0 > 0; \text{ pf: } \int_{-t_0}^{\infty}$$

ROC same

$$\text{Freq shift } f(t)e^{s_0 t} \rightarrow F(s-s_0) \quad \Re(s) > \sigma_0 + \Re(s_0)$$

$\Re(s) > \sigma_0 + \Re(s_0)$

$$\text{Scaling } (a > 0), f(at) \rightarrow \frac{1}{|a|} F\left(\frac{s}{a}\right) \quad \Re(s) > a\sigma_0$$

$\Re(s) > a\sigma_0$

$$\text{Convolution } f_1 * f_2 \rightarrow F_1 F_2$$

ROC  $\cap$

$$f_1 f_2 \rightarrow \frac{1}{2\pi j} F_1 * F_2$$

$$\text{Time diff } \dot{f}(t) \rightarrow sF(s) - f(0^-) \quad \Re(s) > \max(\sigma_0, 0)$$

$$\ddot{f}(t) \rightarrow s^2 F(s) - sf(0^-) - \dot{f}(0^-) \quad \text{pf (parts): } \int_0^\infty \dot{f}(t) e^{-st} dt = [f(t) e^{-st}]_{0^-}^\infty + sF(s)$$

$$\text{Time int } \int_0^\infty f(\tau) d\tau \rightarrow \frac{1}{s} F(s) \quad \text{pf: diff}$$

$$\text{Freq diff } -tf(t) \rightarrow \frac{dF(s)}{ds}$$

$$\text{Freq int } \frac{1}{t} f(t) \rightarrow \int_s^\infty F(z) dz$$

$$\text{IVT } f(0^+) = \lim_{s \rightarrow \infty} sF(s) \quad \text{if exists}$$

$$\text{pf: } \mathcal{L}[f(t)] = \int_0^\infty \dot{f}(t) e^{-st} dt$$

$$\begin{aligned} sF(s) - f(0^-) &= \int_0^{0^+} \dot{f}(t) e^{-st} dt + \int_{0^+}^\infty \dot{f}(t) e^{-st} dt \\ sF(s) - f(0^-) &= f(0^+) - f(0^-) \end{aligned}$$

$$\text{FVT } f(\infty) = \lim_{s \rightarrow 0} sF(s) \quad \text{if exists}$$

$$\text{pf: } \mathcal{L}[f(t)] = \int_0^\infty \dot{f}(t) e^{-st} dt$$

$$\lim_{s \rightarrow 0} sF(s) - f(0^-) = \lim_{s \rightarrow 0} \int_0^\infty \dot{f}(t) e^{-st} dt$$

$$sF(s) - f(0^-) = f(\infty) - f(0^-)$$

## Rational $\mathcal{L}^{-1}$

First rationalize

$$\begin{aligned} F(s) &= \frac{b_m s^m + \dots + b_1 s + b_0}{s^n + \dots + a_1 s + a_0} \equiv \frac{P(s)}{Q(s)} \\ &= \frac{a_0}{(s-\lambda)^r} + \dots + \frac{a_{r-1}}{s-\lambda} + \frac{k_1}{s-\lambda_1} + \dots \\ k &= (s - \lambda_i) F(s)|_{s=\lambda_i} \end{aligned}$$

$$a_0 = (s - \lambda) F(s)|_{s=\lambda}$$

$$a_m = \frac{1}{m!} \frac{d^m}{ds^m} [(s - \lambda)^r F(s)]|_{s=\lambda}$$

$$\mathcal{L}^{-1}\left[\frac{1}{(s-\lambda)^n}\right] = \frac{1}{(n-1)!} t^{n-1} e^{\lambda t} u(t)$$

Multiply both by  $s$  and let  $s = \infty$ , only  $\frac{1}{s}$  term left

## Sys Anal

$$Q(D)y(t) = P(D)f(t)$$

$$H(s) = \frac{Y_{zs}(s)}{F(s)} = \frac{P(s)}{Q(s)}$$

Asym. (internal, init):  $y_{zi}(t) \rightarrow 0$  as  $t \rightarrow \infty$

marginal:  $y_{zi}(t)$  remains bounded (unique  $\lambda$ s on Im axis)

BIBO (external, input) iff  $\int_{-\infty}^{\infty} |h(t)| dt$  exists

$$\Rightarrow |f(t)| < K$$

$$\begin{aligned} y_{zs}(t) &= h * f = \int h(\tau)f(t-\tau)d\tau \\ &\leq \int |h(\tau)||f(t-\tau)|d\tau < K \int |h(\tau)|d\tau \\ \Leftarrow \text{Let } f(t) &= \text{sgn}(h(-t)) \\ y(0) &= \int h(\tau)f(0-\tau)d\tau \\ &= \int h(\tau)\text{sgn}(h(\tau))d\tau \\ &= \int |h(\tau)|d\tau \equiv \infty \end{aligned}$$

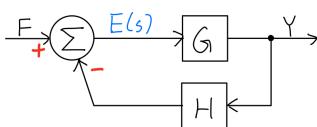
Asy stable  $\Rightarrow$  BIBO stable (all exp)

Marginal  $\Rightarrow$  BIBO unstable ( $\int |\sin(t)| dt = \infty$ )

## Sys Realization

Feedback:  $Y = GE = G(F - HGY)$

$$H_{\text{eff}} = \frac{Y}{F} = \frac{G}{1+HG}$$

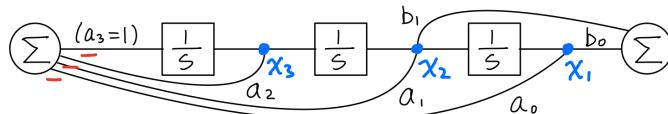


## Canonical

$$\begin{aligned} F(s) &= 1s^3X + a_2s^2X + a_1sX + a_0X \\ s^3X &= F - a_2s^2X - a_1sX - a_0X \end{aligned}$$

$$b_3s^3X + b_2s^2X + b_1sX + b_0X = Y(s)$$

$$H = \frac{b_1s+b_0}{1s^3+a_2s^2+a_1s+a_0}$$



$$\begin{aligned} \left[ \begin{array}{l} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{array} \right] &= \left[ \begin{array}{ccc} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -a_0 & -a_1 & -a_2 \end{array} \right] \left[ \begin{array}{l} x_1 \\ x_2 \\ x_3 \end{array} \right] + \left[ \begin{array}{l} 0 \\ 0 \\ 1 \end{array} \right] f \\ y &= \left[ \begin{array}{l} b_0 \\ b_1 \\ 0 \end{array} \right] \cdot \mathbf{x} \end{aligned}$$

Second form:

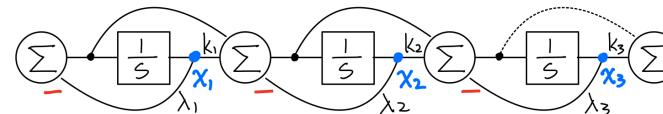
$$s^2Y = s^2b_2F + s(-a_1Y + b_1F) + (-a_0Y + b_0F)$$

$$Y = b_2F + \frac{1}{s}(-a_1Y + b_1F) + \frac{1}{s^2}(-a_0Y + b_0F)$$

Transpose  $\mathbf{A}$ , swap and trans  $\mathbf{b}$ ,  $\mathbf{c}$

## Cascade (made $P_3(s)$ constant here)

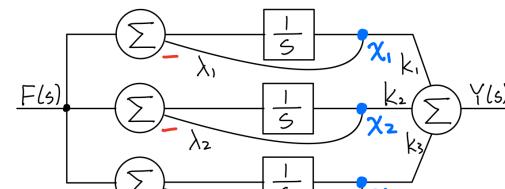
$$H = \frac{P_1(s)}{s+\lambda_1} \cdot \frac{P_2(s)}{s+\lambda_2} \cdot \frac{k_3}{s+\lambda_3}$$



$$\begin{aligned} \left[ \begin{array}{l} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{array} \right] &= \left[ \begin{array}{ccc} -\lambda_1 & 0 & 0 \\ .. & -\lambda_2 & 0 \\ .. & .. & -\lambda_3 \end{array} \right] \left[ \begin{array}{l} x_1 \\ x_2 \\ x_3 \end{array} \right] + \left[ \begin{array}{l} 1 \\ .. \\ .. \end{array} \right] f \\ y &= \left[ \begin{array}{l} 0 \\ 0 \\ k_3 \end{array} \right] \cdot \mathbf{x} \end{aligned}$$

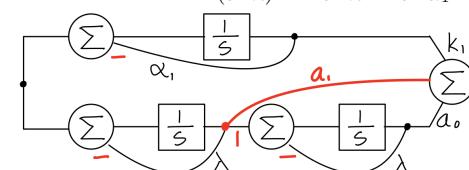
## Parallel

$$H = \frac{k_1}{s+\lambda_1} + \frac{k_2}{s+\lambda_2} + \frac{k_3}{s+\lambda_3}$$



$$\begin{aligned} \left[ \begin{array}{l} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{array} \right] &= \left[ \begin{array}{ccc} -\lambda_1 & 0 & 0 \\ 0 & -\lambda_2 & 0 \\ 0 & 0 & -\lambda_3 \end{array} \right] \left[ \begin{array}{l} x_1 \\ x_2 \\ x_3 \end{array} \right] + \left[ \begin{array}{l} 1 \\ 1 \\ 1 \end{array} \right] f \\ y &= \left[ \begin{array}{l} k_1 \\ k_2 \\ k_3 \end{array} \right] \cdot \mathbf{x} \end{aligned}$$

$$(same pole) H = \frac{a_0}{(s-\lambda)^2} + \frac{a_1}{s-\lambda} + \frac{k_1}{s-\alpha_1}$$



$$\left[ \begin{array}{l} \dot{x}_1 \\ \dot{x}_2 \end{array} \right] = \left[ \begin{array}{cc} 0 & 1 \\ 0 & 0 \end{array} \right] \left[ \begin{array}{l} x_1 \\ x_2 \end{array} \right] + \left[ \begin{array}{l} 0 \\ 1 \end{array} \right] f$$

$$y = \left[ \begin{array}{l} b_0 \\ b_1 \\ 0 \end{array} \right] \cdot \mathbf{x}$$

## State Equations

Def: state of a sys at any time  $t_0$  is the *smallest* set of nums  $\{x_i(t_0)\}$  that is sufficient to determine sys behavior  $\forall t > t_0$  when input  $f(t)$  is known for  $t > t_0$

Always  $\int$  output

If  $t_0 = 0$ , initial condition

$$\dot{\mathbf{x}} = \mathbf{Ax} + \mathbf{bf}$$

$$y = \mathbf{c} \cdot \mathbf{x}$$

MIMO

$$\dot{\mathbf{x}} = \mathbf{Ax} + \mathbf{Bf}$$

$$\mathbf{y} = \mathbf{Cx} + \mathbf{Df}$$

$$s\mathbf{X}(s) - \mathbf{x}(0) = \mathbf{AX}(s) + \mathbf{BF}(s)$$

$$(s\mathbf{I} - \mathbf{A})\mathbf{X}(s) = \mathbf{x}(0) + \mathbf{BF}(s)$$

$$\mathbf{X}(s) = (s\mathbf{I} - \mathbf{A})^{-1}\mathbf{x}(0) + (s\mathbf{I} - \mathbf{A})^{-1}\mathbf{BF}(s)$$

$$\mathbf{x}(t) = \mathbf{x}_{zi}(t) + \mathbf{x}_{zs}(t)$$

## LTI Freq Response

$$H(\omega) = H(s)|_{s=j\omega} = \frac{P(s)}{Q(s)}$$

Ideal delay:  $|H| = 1, \angle H(\omega) = -\omega T$

Ideal diff:  $|H(\omega)| = |\omega|, \angle H(\omega) = \pm \frac{\pi}{2}$

Ideal int:  $|H(\omega)| = \frac{1}{|\omega|}, \angle H(\omega) = \mp \frac{\pi}{2}$

$$f(t) = C = Ce^{0t}$$

$$y(t) = H(0)C$$

$$f(t) = e^{st}$$

$$y(t) = h(t) * e^{st} = e^{st} \int h(\tau)e^{-s\tau}d\tau \equiv H(s)e^{st}$$

$$f(t) = e^{j\omega_0 t} u(t)$$

$$Y_{zs}(s) = F(s)H(s)$$

$$\begin{aligned} &= \frac{1}{s-j\omega_0} \frac{P(s)}{(s-\lambda_1) \dots (s-\lambda_n)} \\ &= \frac{H(s)|_{s=j\omega_0}}{s-j\omega_0} + \frac{k_1}{s-\lambda_1} + \dots \end{aligned}$$

$$y_{zs}(t) = H(\omega_0)e^{j\omega_0 t} u(t) + \sum_i k_i e^{\lambda_i t} u(t)$$

$y_{ss}(t)$  scaled input

$y_{tr}(t)$  decays for stable sys

$$f(t) = \cos(\omega_0 t + \theta) u(t)$$

$$y_{ss}(t) = |H(\omega_0)| \cos(\omega_0 t + \theta + \angle H(\omega_0)) u(t)$$

## Pole Zero

$$\begin{aligned} H(j\omega) &= b_n \frac{(j\omega - z_1) \dots (j\omega - z_n)}{(j\omega - p_1) \dots (j\omega - p_n)} \\ &\equiv b_n \frac{(r_1 e^{j\phi_1}) \dots (r_n e^{j\phi_n})}{(d_1 e^{j\theta_1}) \dots (d_n e^{j\theta_n})} \end{aligned}$$

$$|H(\omega)| = b_n \frac{r_1 \dots r_n}{d_1 \dots d_n}$$

$$\angle H(\omega) = (\phi_1 + \dots + \phi_n) - (\theta_1 + \dots + \theta_n)$$

Vector from p/z to  $j\omega$

Pole enhances gain; Zero suppresses