

# Opamp Characteristics and Amplifier Design

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In the oscilloscope screenshots,  $v_{in}$  vs.  $t$  is in yellow, and  $v_{out}$  vs.  $t$  is in green unless otherwise specified.

## 1 Opamp Performance

### 1.1 Saturation

$v_+$  is connected to  $v_{in}$  and  $v_-$  is connected to ground. Due to the high open-loop gain,  $v_{out}$  saturates positively when  $v_{in} > 0$  and negatively when  $v_{in} < 0$ .

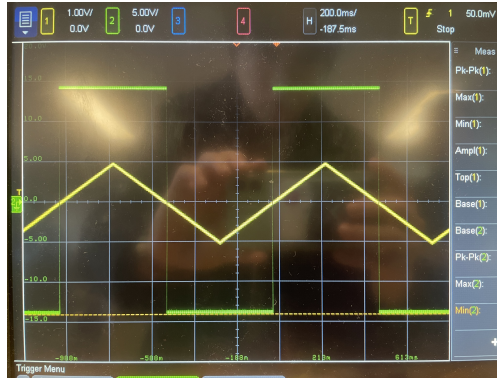


Figure 1: Scope screenshot

### 1.2 Output Voltage Swing



Figure 2: Screenshot for XY output swing

With a  $2\text{ k}\Omega$  resistor as load, the maximum output is  $14.4\text{ V}$ , and the minimum is  $-13.7\text{ V}$ . This is consistent with the data sheet's typical voltage swing of  $\pm 13\text{ V}$ .

### 1.3 Large Signal Voltage Gain

Due to the high opamp gain, we need a small input voltage to accurately measure the gain.

We input a  $V_p = 1 \text{ mV}$  triangular wave at  $1 \text{ Hz}$ . However, at this small input voltage, significant noise is present. We estimated the gain by extrapolating the slope.

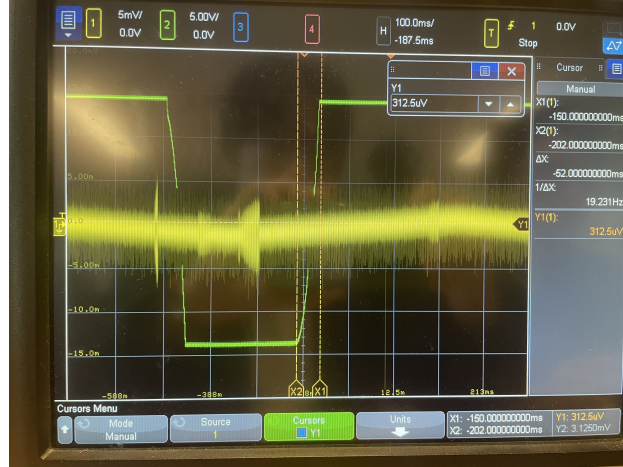


Figure 3: Screenshot for a small input

The slope of the triangular wave is  $\frac{1 \text{ mV} - (-1 \text{ mV})}{0.5 \text{ s}} = 4 \text{ mV/s}$

The output voltage switches from  $-13.7 \text{ V}$  to  $14.4 \text{ V}$  in  $52 \text{ ms}$ . In this  $52 \text{ ms}$  period,  $\Delta v_{in} = 4 \text{ mV/s} \cdot 52 \text{ ms}$

$$\begin{aligned} A &= \frac{\Delta v_{out}}{\Delta v_{in}} \\ &= \frac{14.4 \text{ V} - (-13.7 \text{ V})}{4 \text{ mV/s} \cdot 52 \text{ ms}} \\ &\approx 135 \text{ V/mV} \end{aligned}$$

Our temperature is close to  $25^\circ \text{C}$ .  $20 \text{ V/mV} < 135 \text{ V/mV} < 200 \text{ V/mV}$ . Our large-signal voltage gain is below the typical value, but above the minimal value, so it's acceptable.

### 1.4 Short Circuit Current

Finally, the function generator is replaced by a fixed DC source of  $10 \text{ V}$ , and the output is shorted to ground through an ammeter.

The short circuit current is  $27.2 \text{ mA}$ , which is around the typical value of  $25 \text{ mA}$ .



Figure 4:  $i_{sc}$  measurement



## 2 Unity Gain Buffer

### 2.1 DC Input

I would expect  $v_{out}$  to be the same as  $v_{in}$ . When  $v_{in} = 0$ ,  $v_{out} = 0$  as well. This is verified by our output measurement:  $v_{out} = 0$  V.

The ammeter, shorted from  $v_+$  to ground, does not read any current to its precision of  $1 \mu\text{A}$ . It is unable to read the input bias current on the order of  $80$  to  $500 \text{ nA}$ , as specified by the data sheet.



Figure 5: DC  $i_+$  measurement

### 2.2 AC Input

Now the  $v_+$  is driven by a sine wave  $v_{out} = v_{in}$ . The ammeter, now set to measure AC current, again cannot measure anything to its precision. According to the data sheet, the input offset current is on the order of  $20$  to  $200 \text{ nA}$ , so our ammeter cannot read anything.



Figure 6: AC  $i_+$  measurement

$v_{out}$  follows  $v_{in}$ , as shown by the overlapping traces below:

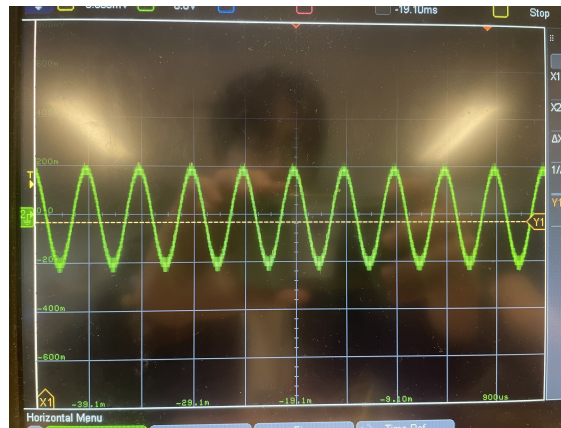


Figure 7: Screenshot of  $v_{in}$  (yellow) and  $v_{out}$  (green). The traces overlap.

- (a) The bias current is within specification, within the limits of our measurement precision.
- (b) The assumption that "opamp draws no current at its input terminals" is valid.
- (c) The virtual short assumption is also valid, as  $v_{out} = v_N = v_P$ . Both input terminals are virtually shorted with proper negative feedback.

### 3 Unity Gain Buffer vs. Voltage Divider

When a  $5\text{ k}\Omega$  resistor is added to the opamp input, the output remains the same.

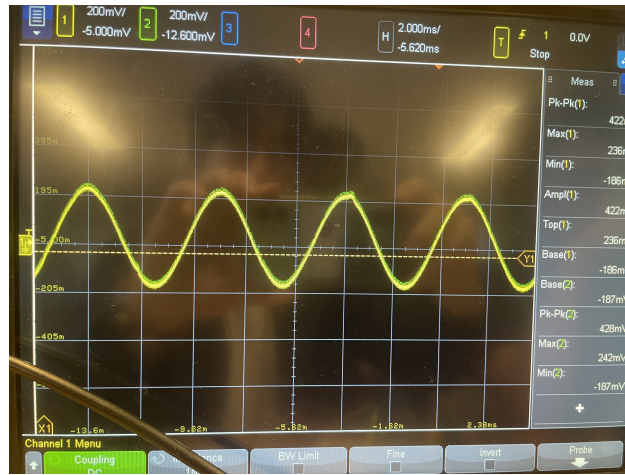


Figure 8: Screenshot with opamp. The input/output traces overlap.

Then the opamp is removed, and the  $5\text{ k}\Omega$  resistor is connected directly to the  $2\text{ k}\Omega$ .



Figure 9: Screenshot without the opamp.

$v_{out}$  is significantly smaller than  $v_{in}$ . There is a significant voltage drop, because the output resistance of the previous stage divides the output voltage. In fact,  $\frac{V_{out,pp}}{V_{in,pp}} = \frac{124\text{ mV}}{422\text{ mV}} \approx \frac{2}{7} = \frac{2\text{ k}\Omega}{5\text{ k}\Omega + 2\text{ k}\Omega}$ .

A unity gain buffer "buffers" out any output resistance of the previous stage because the opamp essentially has infinite input impedance, blocking any input current and, therefore blocking voltage drop.

## 4 Inverting Amplifier

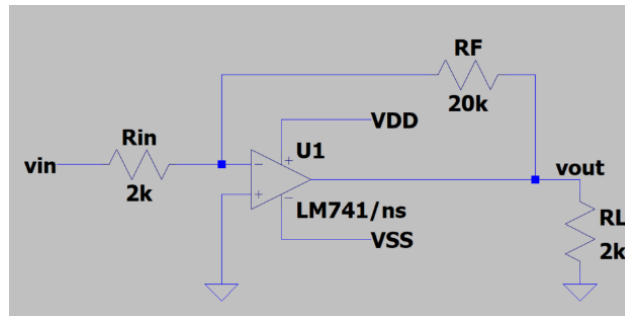


Figure 10: Circuit schematic of the inverting amplifier

$$A_v = -\frac{R_f}{R_{in}} = -\frac{20\text{ k}\Omega}{2\text{ k}\Omega} = -10$$

Result under a 2 k $\Omega$  load:

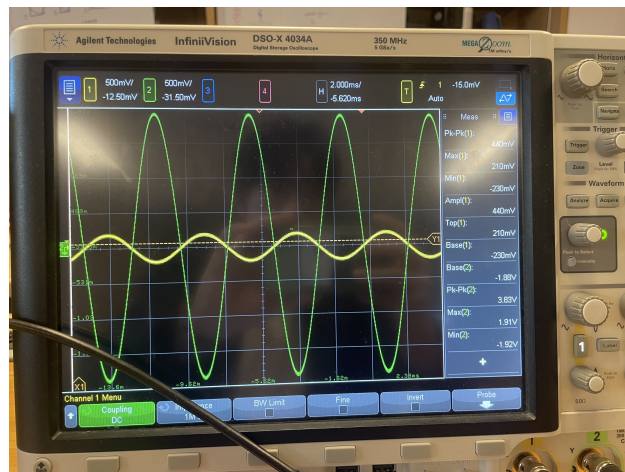


Figure 11: Screenshot for result

## 5 Variable-gain Inverting Amplifier

We used a potentiometer to vary the  $R_f$  and vary the gain.

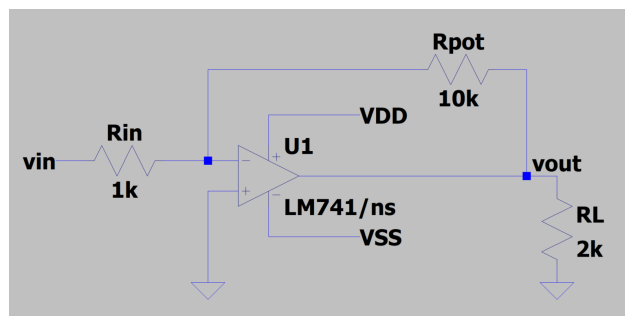


Figure 12: Circuit schematic of the inverting amplifier with variable gain

- When  $R_{pot} = 0$ ,  $A_v = -\frac{R_2}{R_{in}} - \frac{0}{1\text{k}\Omega} = 0$ .
- When  $R_{pot} = 5\text{ k}\Omega$ ,  $A_v = -\frac{R_2}{R_{in}} = -5$
- When  $R_{pot} = 10\text{ k}\Omega$ ,  $A_v = -\frac{R_2}{R_{in}} = -10$ .

## 5.1 Result

Results under a  $2\text{ k}\Omega$  load. The vertical scales differ for  $v_{in}$  and  $v_{out}$ .

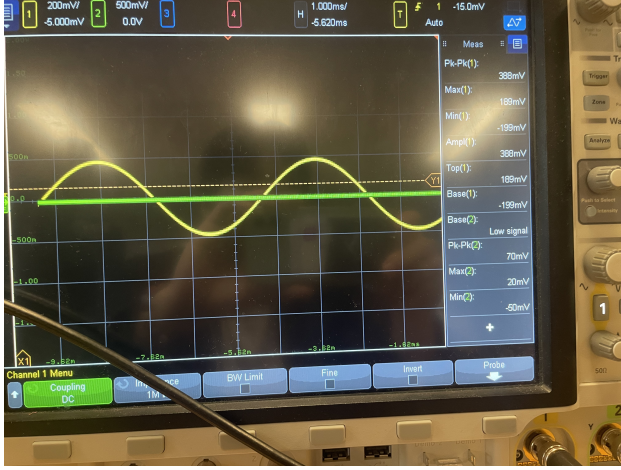


Figure 13:  $A_v = 0$



Figure 14:  $A_v = -5$

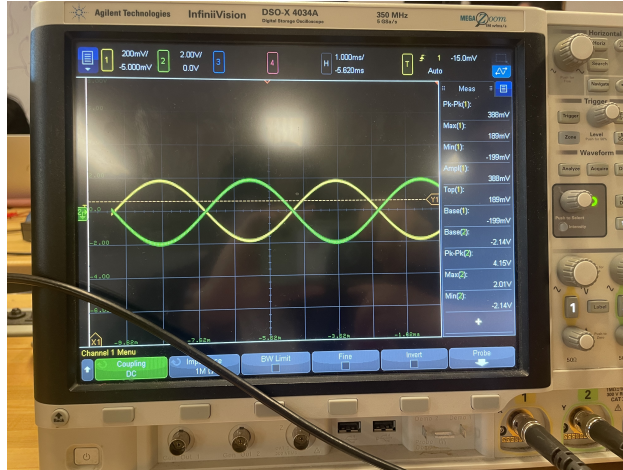


Figure 15:  $A_v = -10$

## 6 Non-inverting Amplifier

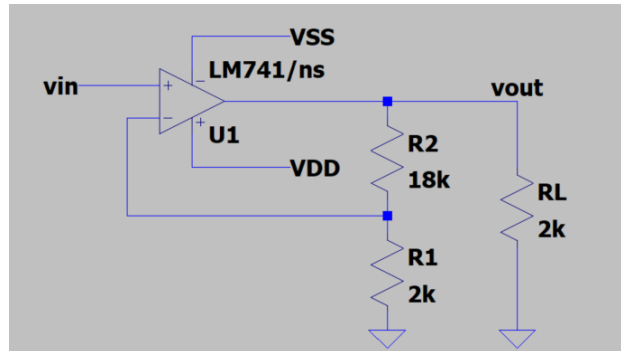


Figure 16: Circuit schematic for the noninverting amplifier with a gain of 10

$$A_v = 1 + \frac{R_2}{R_1} = 1 + \frac{18\text{ k}\Omega}{2\text{ k}\Omega} = 10$$

Result under a  $2\text{ k}\Omega$  load:



Figure 17: Screenshot of the result.  $A_v = 10$ .

## 7 Non-inverting Amplifier with Variable Gain

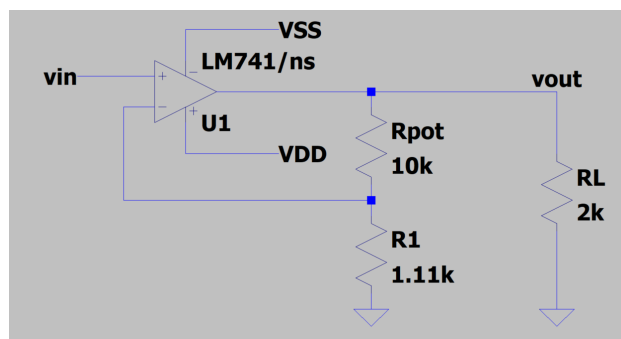


Figure 18: Circuit schematic for the variable noninverting amplifier.



- When  $R_{pot} = 0$ ,  $A_v = 1 + \frac{R_2}{R_{in}} = 1$ .
- When  $R_{pot} \approx 4.44 \text{ k}\Omega$ ,  $A_v = 1 + \frac{R_2}{R_1} = 5$
- When  $R_{pot} = 10 \text{ k}\Omega$ ,  $A_v = 1 + \frac{R_2}{R_1} = 10$ .

Results under a  $2 \text{ k}\Omega$  load:

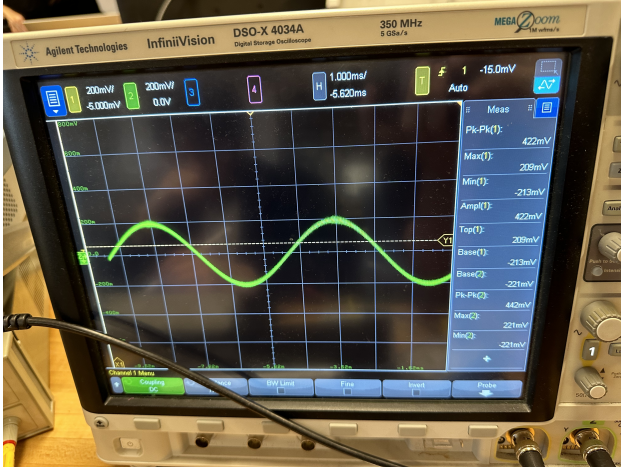


Figure 19:  $A_v = 1$

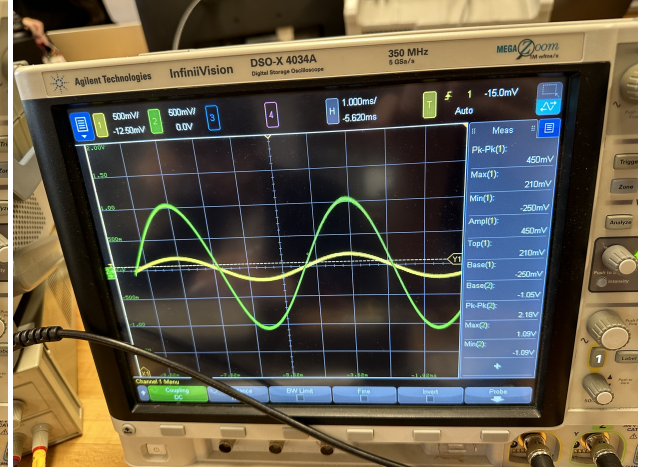


Figure 20:  $A_v = 5$

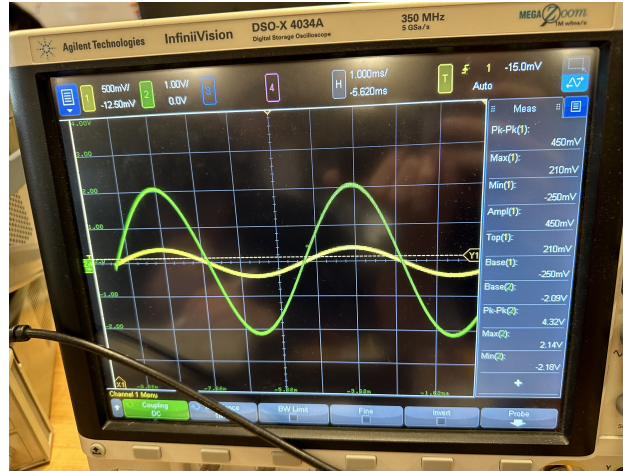


Figure 21:  $A_v = 10$ . The output scale is twice the input scale.



## 8 Summing Amplifier

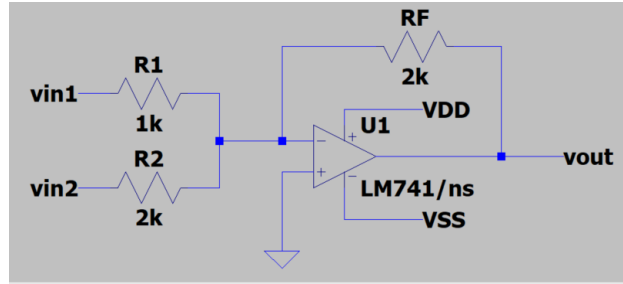


Figure 22: Circuit schematic for the summing amplifier

$$v_{out} = -\frac{R_F}{R_1}v_{in1} - \frac{R_F}{R_2}v_{in2} = -\frac{2\text{ k}\Omega}{1\text{ k}\Omega}v_1(t) - \frac{2\text{ k}\Omega}{2\text{ k}\Omega}v_2(t) = -(2v_1(t) + v_2(t))$$

$v_1(t)$  is driven with a sinusoid, and  $v_2(t)$  is driven with a square wave of the same peak amplitude and frequency.

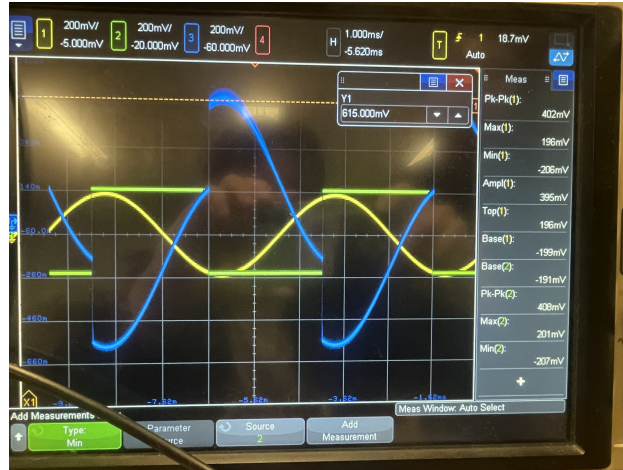


Figure 23: Screenshot with  $v_1(t)$  in yellow,  $v_2(t)$  is green, and output in blue

## 9 Difference Amplifier

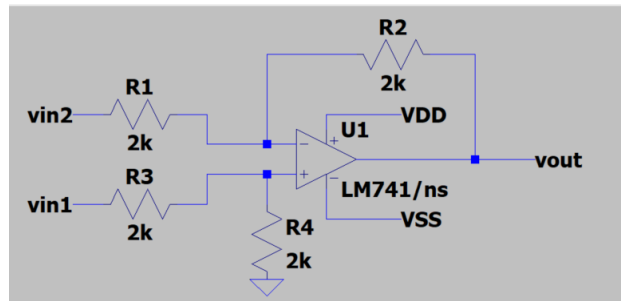


Figure 24: Circuit schematic for the difference amplifier

By setting  $\frac{R_3}{R_4} = \frac{R_1}{R_2}$ ,

$$v_{out} = \frac{R_2}{R_1}(v_{in1} - v_{in2}) = \frac{2\text{k}\Omega}{2\text{k}\Omega}(v_1(t) - v_2(t))$$

$v_1(t)$  is driven with a sinusoid, and  $v_2(t)$  is driven with a square wave of the same peak amplitude and frequency.



Figure 25: Screenshot with  $v_1(t)$  in yellow,  $v_2(t)$  is green, and output in blue